Curriculum Vitae JEFFREYA. CALEY

Oregon State University 204 Graf Hall Corvallis, Oregon 97331

360.560.0025 jeff.caley@gmail.com

Education

Oregon State University: Corvallis, OR, 2014-June 2019

PhD - Robotics - Collaborative Robotics and Intelligent Systems (CoRIS) Institute Thesis Topic: Deep Learning for Robotic Exploration Adviser: Geoff Hollinger

Portland State University: Portland, OR, 2010-2013

Masters of Science, Electrical and Computer Engineering Thesis Topic: A Survey of Systems for Predicting Stock Market Movements, Combining Market Indicators and Machine Learning Classifiers Adviser: Richard Tymerski

Pacific Lutheran University: Tacoma, WA, 2003-2007

Bachelor of Science, Computer Engineering Adviser: Tosh Kakar

Research and Industry Experience

Oregon State University

Robotic Decision Making Laboratory - Research Assistant Researcher in the Robotic Decision Making Laboratory under Dr. Geoff Hollinger. Exploring autonomous decision making in underwater robotics using deep learning.

Pacific Lutheran University

Visiting Instructor of Computer Science and Engineering Created and delivered dynamic and engaging lectures and activities to further students knowledge in the engineering field.

Cocollage

Chief Operations Officer. Co-Founder

Duties included recruiting development team, managing hardware distribution, Financial estimates, budget, interdisciplinary coordination of requirements and development, project management.

2013-2014

2014-2019

2010 - 2013

Boeing	2008-2013
Programmer Analyst 1	2008-2009
Programmer Analyst 2	2009-2012
Programmer Analyst 3	2012-2013
Sys Design & Integ Spec 3	2013-2013
Microsoft	2007
Software Test Engineer	
Cyber Camps	2006
Camp Director - Fort Lewis Division	

Teaching Experience

Instructor 2013 - 2014

Pacific Lutheran CSCE131: Introduction to Engineering Pacific Lutheran CSCE331: Electrical Circuits Pacific Lutheran CSCE345: Microelectronics

Teaching Assistant 2010

Portland State ECE510: Computational Finance - 2013 Pacific Lutheran CSCE144: Introduction to Computer Science - 2006 Oregon State ROB534: Sequential Decision Making in Robotics - 2019

Conference and Journal Papers

Caley, Jeffrey A., Lawrance, Nicholas R.J., and Geoffrey A. Hollinger. "Environment Prediction from Sparse Samples for Robotic Information Gathering" International Conference on Robot Learning (CoRL19), Submitted 2019

Caley, Jeffrey A., Lawrance, Nicholas R.J., and Geoffrey A. Hollinger. "Deep Learning of Structured Environments for Robot Search" Journal of Autonomous Robots, Jan 2019

Caley, Jeffrey A., Lawrance, Nicholas R.J., and Geoffrey A. Hollinger. "Deep Networks with Confidence Bounds for Robotic Information Gathering" in Proc. Robotics: Science and Systems Conf. Workshop on New Frontiers for Deep Learning in Robotics (RSS17), Boston, MA, July, 2017.

Caley, Jeffrey A., Lawrance, Nicholas R.J., and Geoffrey A. Hollinger. "Deep Learning of Structured Environments for Robot Search" In Proc. International Conference on Intelligent Robots and Systems (IROS), 2016.

Caley, Jeffrey A., and Geoffrey A. Hollinger. "Data-driven comparison of spatio-temporal monitoring techniques." In Proc. OCEANS 2015-MTS/IEEE Washington. IEEE, 2015.

Service

Associated Students of Oregon State University House of Representative 2018-2019 Oregon State robotics tour guide 2015-current Coalition of Graduate Employees Union Steward 2018-current PLU Industry Advisory Board Member 2008-Current Co-founded Deep Learning reading group OSU 2017-current Faculty Evaluation Committee 2018

Outreach

Washington Aerospace Scholars Program 2012-2014 PLU Capstone mentor 2017-2018 PLU High School Programming Contest judge 2016-2018

Invited Talks

"Deep Learning of Structured Environments for Robot Search" Robotics Seminar at Oregon State University, Corvallis, OR, November 2016

"Probabilistic Robotics: Why Grad School and Robots are Awesome" Tech Talk at Pacific Lutheran University, Parkland, WA, September 2017